

# Common Fixed Point Results for Asymptotic Quasi-Contraction Mappings in Quasi-Metric Spaces

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## Abstract

In this article, two new classes of pairs  $\{T, f\}$  consisting of an asymptotic quasi-contraction  $T$  with respect to a map  $f$  are introduced. The existence and uniqueness of the common fixed point of such pairs  $\{T, f\}$  is then established in the context of a quasi-metric space  $X$ , when  $T$  and  $f$  are weakly compatible. The theorems obtained rely on some conditions on the orbit  $O_{T,f}(x, \infty)$  of  $T$  at points  $x \in X$  with respect to  $f$ , and are in fact, improvements of previously known results in the literature of metric-types. An example is given to validate the results obtained.

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**MSC2010:** 32H50, 47H10.

## 1 Introduction

There are many generalizations of the fundamental contraction mapping theorem established by Banach [1] which served as pivotal tool for solving problems in analysis and applied mathematics. For instance see [2-6]. One of the most general contraction mapping was introduced by Ciric [7] in 1971. In 2003, Kirk [8] introduced asymptotic contraction mapping which is a generalization of Banach contraction mapping and established the fixed point of the operator in a complete metric space under certain conditions. Asymptotic contraction map is for example, applied in dynamical system to solve analytical problems. Several works have been carried out in this regard, see [9, 10]. Meir-keeler [11] extended Banach contraction principle by proving the following result:

Let  $(X, d)$  be a complete metric space and  $f$  a self map of  $X$ .  
Assume that for every  $\epsilon > 0$ , there exists  $\delta > 0$  such that:  
 $\epsilon \leq d(x, y) < \epsilon + \delta$  implies  $d(fx, fy) < \epsilon$  for all  $x, y \in X$ .  
Then  $f$  has a unique fixed point.

Suzuki [12] combined the works of Kirk [8] and Meir-Keeler [11] to introduce a class of map called asymptotic contraction of Meir-Keeler type (for short, ACMK). In 2008, Singh and Pant [13] extended the result of Suzuki [12] to more general maps. Our interest is in the result of Singh et al. [14] on maps that are called generalized asymptotic contraction of Meir-Keeler type (for short, GACMK).

**Definition 1.1.** Let  $(X, d)$  be a metric space,  $Y$  a subset of  $X$ , and  $T, f : Y \rightarrow X$  two maps. The map  $T$  is called a generalized asymptotic contraction of Meir-Keeler type (in short GACMK) with respect to  $f$  if there is a sequence  $\{\psi_n\}$  of self-maps on  $[0, \infty)$  such that:

- (P<sub>1</sub>)  $\limsup_{n \rightarrow \infty} \psi_n(\epsilon) \leq \epsilon$  for all  $\epsilon \geq 0$ ;
- (P<sub>2</sub>) for each  $\epsilon > 0$ , there exist  $\delta > 0$  and  $\nu \in \mathbb{N}$  such that  $\psi_\nu(t) \leq \epsilon$  for all  $t \in [\epsilon, \epsilon + \delta]$ ;
- (P<sub>3</sub>)  $d(T^n x, T^n y) < \psi_n(M(x, y))$  for all  $n \in \mathbb{N}$  and  $x, y \in X$  with  $M(x, y) > 0$ , where  $M(x, y) = \max \left\{ d(fx, fy), d(fx, Tx), d(fy, Ty), \frac{d(fx, Ty) + d(fy, Tx)}{2} \right\}$ .

In the same reference, they stated the following result.

**Theorem 1.2.** Let  $(X, d)$  be a metric space and  $T, f : Y \rightarrow X$  such that  $T(Y) \subseteq f(Y)$ . Let  $T$  be a GACMK with respect to  $f$ . If  $T(Y)$  or  $f(Y)$  is a complete subspace of  $X$ , then  $T$  and  $f$  have a coincidence point. Further, if  $Y = X$ , then  $T$  and  $f$  have a unique common fixed point provided that  $T$  and  $f$  commute at a coincidence point.

Recall that the following definitions of coincidence points and weakly compatible mappings:

**Definition 1.3.** [15] Let  $X$  be a set and  $T$  and  $f$  be two self maps of  $X$ . A point  $x$  in  $X$  is called a coincidence point of  $T$  and  $f$  if and only if  $Tx = fx$ . We shall call  $z := Tx = fx$  a point of coincidence of  $T$  and  $f$ .

**Definition 1.4.** [16] Two self maps  $T$  and  $f$  in a set  $X$  are said to be weakly compatible if they commute at their points of coincidence, that is, if  $Tx = fx$  for some  $x \in X$ , then  $Tfx = fTx$ .

It should be noted that Definition 1.1 and Theorem 1.2 due to Singh et al. [14] pose a few problems:

1. for  $x \in X$  and  $n \in \mathbb{N}$ , the point  $T^n x$  is not defined, except if  $Y = X$ ;
2. the function  $f$  may not satisfy  $f(x) = x$  for all  $x \in Y$ . Therefore, a sequence<sup>1</sup>  $\{x_n\}$  such that  $Tx_n = fx_{n+1}$  for all  $n \geq 0$ , may not satisfy  $x_n = T^n x_0$  for all  $n \geq 0$ , an assumption which seem to have been used in several lines of their proof.

In this paper, our aim is to provide an amendment of the maps of Singh et al. [14] and establish an ensing common fixed point theorem in the framework quasi-metric spaces. The following are needed definitions in the setting of quasi-metric spaces:

**Definition 1.5.** [17] Let  $X$  be a non-empty set. A function  $d : X \times X \rightarrow [0, \infty)$  is said to be a quasi-metric on  $X$  if for any  $x, y, z \in X$  the following holds:

- (i)  $d(x, y) = 0$  if and only if  $x = y$ ;
- (ii)  $d(x, z) \leq d(x, y) + d(y, z)$ .

In such case,  $(X, d)$  is said to be a quasi-metric space.

**Definition 1.6.** [17-20] Let  $(X, d)$  be a quasi-metric space. A sequence  $\{x_n\}$  in  $X$  is said to be:

- (i) forward-convergent to some  $x \in X$  (called the forward limit) if  $\forall \epsilon > 0 \exists N_\epsilon \in \mathbb{N} : d(x_n, x) < \epsilon \forall n \geq N_\epsilon$ ; in other words,  $\{x_n\}$  in  $X$  is forward-convergent to  $x$  if  $\lim_{n \rightarrow \infty} d(x_n, x) = 0$ .

<sup>1</sup>The existence of such a sequence is discussed in subsection 2.1.

- (ii) backward-convergent to some  $x \in X$  (called the backward limit) if  $\forall \epsilon > 0 \exists N_\epsilon \in \mathbb{N}: d(x, x_n) < \epsilon \forall n \geq N_\epsilon$ ; in other words,  $\{x_n\}$  in  $X$  is backward-convergent to  $x$  if  $\lim_{n \rightarrow \infty} d(x, x_n) = 0$ .
- (iii) convergent to some  $x \in X$  if it is both forward-convergent and backward-convergent to  $x$ .
- (iv) forward Cauchy (or left K-Cauchy) if  $\forall \epsilon > 0 \exists N_\epsilon \in \mathbb{N}: d(x_n, x_{n+k}) < \epsilon \forall n \geq N_\epsilon \forall k \in \mathbb{N}$ .
- (v) backward Cauchy (or right K-Cauchy) if  $\forall \epsilon > 0 \exists N_\epsilon \in \mathbb{N}: d(x_{n+k}, x_n) < \epsilon \forall n \geq N_\epsilon \forall k \in \mathbb{N}$ .
- (vi) Cauchy (or p-Cauchy) if  $\forall \epsilon > 0 \exists N_\epsilon \in \mathbb{N}: d(x_n, x_m) < \epsilon \forall n \geq N_\epsilon \forall k \in \mathbb{N}$ . In other words,  $\{x_n\}$  is Cauchy if it is forward Cauchy and backward Cauchy.

**Definition 1.7.** [21] *A quasi-metric space  $X$  is said to be complete if every Cauchy sequence in  $X$  is convergent in  $X$ .*

## 2 Generalized Asymptotic Contractions of Meir-Keeler type with respect to some functions

In the next section, we give ammend the definition of a generalized asymptotic contraction of Meir-Keeler type as proposed by Singh et al. [14], then prove a common fixed point theorem in complete quasi-metric space.

### 2.1 Jungck sequence and orbits with respect to $f$

Suppose  $X$  is a non-empty set,  $Y$  is a non-empty subset of  $X$ , and  $T, f : Y \rightarrow X$  such that  $T(Y) \subseteq f(Y)$ .

Choosing  $x_0 \in Y$ , one can define a Jungck sequence  $\{x_n\}$  of points in  $Y$  such that

$$Tx_n = fx_{n+1}, \quad n = 0, 1, 2, \dots \quad (2.1)$$

If  $f$  is the inclusion map, that is, such that  $f(x) = x$  for any  $x \in Y$ , then by repetitive application of (2.1), the sequence  $\{x_n\}$  is such that  $x_n = T^n x_0$ , or more generally,  $x_{n+k} = T^n x_k$  for any  $n, k \geq 0$ , with the convention that  $T^0$  is the identity function on  $Y$ .

If  $f$  is not necessarily the inclusion map, and  $x \in X$ , the sequence of sets  $\{(Tf^{-1})^n(x)\}_{n \geq 0}$  is defined as follows:

$$(Tf^{-1})^n(x) = \begin{cases} \{x\} & \text{if } n = 0 \\ \{Tu : f(u) = x\} & \text{if } n = 1 \\ \{Tu : f(u) \in (Tf^{-1})^{n-1}(x)\} & \text{if } n > 1. \end{cases} \quad (2.2)$$

Given that  $\emptyset \neq T(Y) \subseteq f(Y)$ , each  $(Tf^{-1})^n(x)$  is non-empty and for  $n > 1$ ,

$$(Tf^{-1})^n(x) = \left\{ Tu \mid \begin{array}{l} \exists u_1, u_2, \dots, u_{n-1} \in Y, f(u) = Tu_1, f(u_{n-1}) = x \\ \text{and if } n > 2, f(u_1) = Tu_2, \dots, f(u_{n-2}) = Tu_{n-1}, \end{array} \right\} \quad (2.3)$$

The Jungck sequence  $\{x_n\}$  defined in (2.1) is such that for all  $n, k \geq 0$ ,  $Tx_{n+k} \in (Tf^{-1})^n(Tx_k)$ , and in particular,  $Tx_n \in (f^{-1}T)^n(Tx_0)$  and  $Tx_{n+1} \in (Tf^{-1})(Tx_n)$ .

Notice that when  $f$  is a bijection on  $Y$ , each  $(Tf^{-1})^n(x)$  is the singleton. In the special case where  $f(x) = x$  for all  $x \in Y$ ,  $(Tf^{-1})^n(x) = \{T^n x\}$  for each  $n \geq 0$  and  $x \in Y$ .

In literature, orbits of self-maps and orbital completeness have been defined as follow:

**Definition 2.1.** [22] Let  $T : X \rightarrow X$  be a self mapping on a metric space. For each  $x \in X$  and for any positive whole number  $n$ , define the sets:

$$O_T(x, n) = \{x, Tx, T^2x, T^3x, \dots, T^n x\}$$

and

$$O_T(x, \infty) = \{x, Tx, T^2x, T^3x, \dots, T^n x, \dots\}.$$

The set  $O_T(x, \infty)$  is called the orbit of  $T$  at  $x$  and the metric space  $X$  is called  $T$ -orbitally complete if every Cauchy sequence in  $O_T(x, \infty)$  is convergent in  $X$ .

The following definition is an extension of the concepts of orbits and orbital completeness for maps for which Jungck sequences are defined:

**Definition 2.2.** Let  $T, f : Y \rightarrow X$  be a two mappings defined on a subset  $Y$  of a set  $X$ , for which  $T(Y) \subseteq f(Y)$ . For each  $x \in X$  and for any positive whole number  $n$ , the set

$$O_{T,f}(x, n) := \{z \mid z \in (Tf^{-1})^i(x), 0 \leq i \leq n\} = \bigcup_{i=0}^n (Tf^{-1})^i(x)$$

will be called the  $n$ -orbit of  $T$  at  $x$  with respect to  $f$ , while the set

$$O_{T,f}(x, \infty) := \{z \mid z \in (Tf^{-1})^i(x), i \geq 0\} = \bigcup_{i=0}^{\infty} (Tf^{-1})^i(x)$$

will be called the orbit of orbit of  $T$  at  $x$  with respect to  $f$ .

If  $X$  is endowed with a quasi-metric  $d$ , then  $X$  is called  $\{T, f\}$ -orbitally complete if every Cauchy sequence in  $O_{T,f}(x, \infty)$  is convergent in  $X$ .

It immediately follows that the well-known concepts of orbits and orbital completeness of a map  $T$  are obtained when  $f(x) = x$  for all  $x \in Y$ . Motre precisely,  $O_{T,f}(x, n)$  becomes  $O_T(x, n)$  and  $O_{T,f}(x, \infty)$  becomes  $O_T(x, \infty)$ .

## 2.2 GACMK re-introduced

We can then re-introduce the definition of Generalized Asymptotic Contraction of Meir-Keeler type (GACMK) with respect to a function  $f$ :

**Definition 2.3.** Let  $(X, d)$  be a quasi-metric space,  $Y$  a subset of  $X$ , and  $T, f : Y \rightarrow X$  two mappings. The map  $T$  is called generalized asymptotic contraction of Meir - Keeler type (GACMK, simply) with respect to  $f$  if there exists a sequence  $\{\psi_n\}$  of functions from  $[0, \infty)$  into itself satisfying the following:

$$(G_1) \limsup_{n \rightarrow \infty} \psi_n(\epsilon) \leq \epsilon \text{ for all } \epsilon > 0;$$

$$(G_2) \text{ for each } \epsilon > 0 \text{ there exist } \delta > 0 \text{ and } \nu \in \mathbb{N} \text{ such that } \psi_\nu(t) \leq \epsilon \text{ for all } t \in [\epsilon, \epsilon + \delta];$$

$$(G_3) \text{ For all } n \in \mathbb{N}, \text{ and } x, y \in Y \text{ such that } M(x, y) > 0,$$

$$d(u, v) < \psi_n(M(x, y)), \tag{2.4}$$

for all  $u \in (Tf^{-1})^{n-1}(Tx)$ ,  $v \in (Tf^{-1})^{n-1}(Ty)$ , where:

$$M(x, y) = \max \left\{ d(fx, fy), d(fx, Tx), d(fy, Ty), \frac{d(fx, Ty) + d(fy, Tx)}{2} \right\}. \tag{2.5}$$

**Remark 2.4.**

1. It should be noted that Definition 2.3 differs with Definition 1.1 proposed by Singh et al. [14] in that the inequality (2.4),  $d(u, v) < \psi_n(M(x, y))$ , holds for any  $u \in (Tf^{-1})^{n-1}(Tx)$  and  $v \in (Tf^{-1})^{n-1}(Ty)$  rather than for  $u = T^n x$  and  $v = T^n y$  (which would only exist if  $Y = X$ ).

2. Suppose  $f(x) = x$  for all  $x \in Y$ , then for any  $x, y \in Y$ , we have that

$$M(x, y) = \max \left\{ d(x, y), d(x, Tx), d(y, Ty), \frac{d(x, Ty) + d(y, Tx)}{2} \right\}$$

and  $(u, v) = (T^n x, T^n y)$  for all  $n \in \mathbb{N}$ ,  $u \in (Tf^{-1})^{n-1}(Tx)$ , and  $v \in (Tf^{-1})^{n-1}(Ty)$ . Under this condition, for any  $n \in \mathbb{N}$ ,  $d(T^n x, T^n y) < \psi_n(M(x, y))$  for  $x, y \in Y$  such that  $M(x, y) > 0$ , and

- (i) if  $\max\{d(x, y), d(x, Tx), d(y, Ty), d(x, Ty), d(y, Tx)\} = d(x, y)$  in (iii) of Definition 2.3,  $T$  becomes an asymptotic contraction of Meir-Keeler type (or simply, ACMK) discussed in by Suzuki [12];
- (ii) the case where  $M(x, y) = \max\{d(x, y), d(x, Tx), d(y, Ty)\}$  for all  $x, y \in X$  is discussed by Singh and Pant [13].

**2.3 A fixed point theorem**

Now we prove the following theorem on the existence and uniqueness of the common fixed point of a pair  $\{T, f\}$  where  $T$  is a GACMK with respect to  $f$ .

**Theorem 2.5.** *Let  $(X, d)$  be a quasi-metric space and  $T, f : Y \rightarrow X$  such that  $T(Y) \subseteq f(Y)$ . Let  $T$  be a GACMK with respect to  $f$ , i.e., such that for all  $n \in \mathbb{N}$  and  $x, y \in Y$  such that  $M(x, y) > 0$ ,*

$$d(u, v) < \psi_n(M(x, y))$$

for any  $u \in (Tf^{-1})^{n-1}(Tx)$  and  $v \in (Tf^{-1})^{n-1}(Ty)$ , where

$$M(x, y) = \max \left\{ d(fx, fy), d(fx, Tx), d(fy, Ty), \frac{d(fx, Ty) + d(fy, Tx)}{2} \right\}.$$

and  $\{\psi_n\}$  is a sequence of self-maps on  $[0, \infty)$  such that:

$$(G_1) \limsup_{n \rightarrow \infty} \psi_n(\epsilon) \leq \epsilon \text{ for all } \epsilon \geq 0;$$

$$(G_2) \text{ for each } \epsilon > 0, \text{ there exist } \delta > 0 \text{ and } \nu \in \mathbb{N} \text{ such that } \psi_\nu(t) \leq \epsilon \text{ for all } t \in [\epsilon, \epsilon + \delta].$$

Suppose further that:

$$(G_4) \text{ any two distinct elements } z_1, z_2 \text{ in } O_{T,f}(x, \infty), \frac{d(z_1, z_2)}{2} < d(z_2, z_1).$$

If  $T(Y)$  or  $f(Y)$  is a complete subspace of  $X$ , then  $T$  and  $f$  have a coincidence point. Further, if  $Y = X$ , then  $T$  and  $f$  have a unique common fixed point provided that  $T$  and  $f$  commute at a coincidence point.

*Proof.* Let  $x_0 \in Y$  be arbitrary chosen. Since  $T(Y) \subset f(Y)$ , we can define a Jungck sequence  $\{x_n\}$  of points in  $Y$ , and a sequence  $\{y_n\}$  in  $X$  such that

$$y_n = Tx_n = fx_{n+1}, \quad n = 0, 1, 2, \dots$$

This means that

$$Tx_{n+k} \in (Tf^{-1})^n(Tx_k) \quad \forall n, k \geq 0, \tag{2.6}$$

and that

$$d(Tx_{n+i}, Tx_{n+j}) < \psi_{n+1}(M(x_i, x_j)) \quad \text{for all } n \geq 0 \text{ and } i, j \text{ with } M(x_i, x_j) > 0. \quad (2.7)$$

**First step:** We prove by cases that  $T$  and  $f$  have a coincidence point if  $T(Y)$  or  $f(Y)$  is complete.

If there is  $n \geq 0$  such that  $Tx_n = Tx_{n+1}$ , then  $x_{n+1}$  is a coincidence point of  $T$  and  $f$ , since  $fx_{n+1} = Tx_{n+1}$ . Suppose now that  $Tx_n \neq Tx_{n+1}$  for all  $n \geq 0$ .

For any  $n \geq 0$ , we have  $d(fx_{n+1}, Tx_{n+1}) = d(Tx_n, Tx_{n+1}) > 0$ , hence  $M(x_i, x_j) > 0$  for any distinct  $i, j \geq 0$ .

For any  $n \geq 1$ ,

$$\begin{aligned} d(Tx_n, Tx_{n+1}) &< \psi_1(M(x_n, x_{n+1})) \\ &\leq M(x_n, x_{n+1}) \\ &= \max \left\{ d(Tx_{n-1}, Tx_n), d(Tx_n, Tx_{n+1}), \frac{d(Tx_{n-1}, Tx_{n+1})}{2} \right\} \\ &\leq \max \{ d(Tx_{n-1}, Tx_n), d(Tx_n, Tx_{n+1}) \}, \end{aligned} \quad (2.8)$$

hence for all  $n \geq 1$ ,

$$\begin{cases} M(x_n, x_{n+1}) &= d(Tx_{n-1}, Tx_n) \\ d(Tx_n, Tx_{n+1}) &< d(Tx_{n-1}, Tx_n). \end{cases} \quad (2.9)$$

Thus, the sequence  $\{d(Tx_n, Tx_{n+1})\}_{n \geq 0}$  is decreasing and bounded below hence converges to some  $\alpha \geq 0$ , and  $d(Tx_n, Tx_{n+1}) > \alpha$  for all  $n \geq 0$ .

Suppose  $\alpha > 0$ . Since  $0 < \alpha < d(Tx_0, Tx_1)$ , there are  $\delta_1 > 0$  and  $\mu_1 \in \mathbb{N}$  such that  $\psi_{\mu_1}(t) \leq \alpha$  for all  $t \in [\alpha, \alpha + \delta_1]$ . By definition of  $\alpha$ , there is  $\mu_2 \in \mathbb{N}$  such that  $M(x_{\mu_2}, x_{\mu_2+1}) = d(Tx_{\mu_2-1}, Tx_{\mu_2}) < \alpha + \delta_1$ . Therefore,  $d(Tx_{\mu_2+\mu_1-1}, Tx_{\mu_2+\mu_1}) < \psi_{\mu_1}(M(x_{\mu_2}, x_{\mu_2+1})) \leq \alpha$ , a contradiction. Thus  $\alpha := \lim_{n \rightarrow \infty} d(Tx_n, Tx_{n+1}) = 0$ .

Next we show that  $\{Tx_n\}$  is forward-Cauchy sequence. Assuming  $\{y_n\}$  is not a forward-Cauchy sequence, there exists  $\beta > 0$  and increasing sequences  $\{m_k\}$  and  $\{n_k\}$  of positive integers such that for all  $k \in \mathbb{N}$ ,  $m_k < n_k$ ,  $d(Tx_{m_k}, Tx_{n_k}) \geq \beta$  and  $d(Tx_{m_k}, Tx_{n_k-1}) < \beta$ . By the triangle inequality,

$$d(Tx_{m_k}, Tx_{n_k}) \leq d(Tx_{m_k}, Tx_{n_k-1}) + d(Tx_{n_k-1}, Tx_{n_k}),$$

and as  $k \rightarrow \infty$ ,  $d(Tx_{m_k}, Tx_{n_k}) \rightarrow \beta$ . We also have that:

$$\begin{aligned} d(Tx_{m_k}, Tx_{n_k}) &< \psi_1(M(x_{m_k}, x_{n_k})) \\ &= \psi_1 \left( \max \left\{ d(Tx_{m_k-1}, Tx_{n_k-1}), d(Tx_{m_k-1}, Tx_{m_k}), \right. \right. \\ &\quad \left. \left. d(Tx_{n_k-1}, Tx_{n_k}), \frac{d(Tx_{m_k-1}, Tx_{n_k}) + d(Tx_{n_k-1}, Tx_{m_k})}{2} \right\} \right), \end{aligned}$$

hence as  $k \rightarrow \infty$ ,  $\beta \leq \psi_1(\beta) < \beta$ , a contradiction. Thus  $\{Tx_n\}$  is a forward-Cauchy sequence.

We may prove similarly that  $\{Tx_n\}$  is a backward-Cauchy sequence. Indeed, for any  $n \geq 0$ , we have  $d(Tx_{n+1}, fx_{n+1}) = d(Tx_{n+1}, Tx_n) > 0$ , hence  $M(x_i, x_j) > 0$  for any distinct  $i, j \geq 0$ . For any  $n \geq 1$ ,

$$\begin{aligned} d(Tx_{n+1}, Tx_n) &< \psi_1(M(x_{n+1}, x_n)) \\ &\leq M(x_{n+1}, x_n) \\ &= \max \left\{ d(Tx_n, Tx_{n-1}), d(Tx_{n+1}, Tx_n), \frac{d(Tx_{n+1}, Tx_{n-1})}{2} \right\} \\ &\leq \max \{ d(Tx_n, Tx_{n-1}), d(Tx_{n+1}, Tx_n) \}, \end{aligned} \quad (2.10)$$

hence for all  $n \geq 1$ ,

$$\begin{cases} M(x_{n+1}, x_n) &= d(Tx_n, Tx_{n-1}) \\ d(Tx_{n+1}, Tx_n) &< d(Tx_n, Tx_{n-1}). \end{cases} \quad (2.11)$$

The sequence  $\{d(Tx_{n+1}, Tx_n)\}_{n \geq 0}$  is decreasing and bounded below hence converges to some  $\gamma \geq 0$ , and  $d(Tx_{n+1}, Tx_n) > \gamma$  for all  $n \geq 0$ . In fact,  $\gamma = 0$  and  $\lim_{n \rightarrow \infty} d(Tx_{n+1}, Tx_n) = 0$ . To see this, assume  $\gamma > 0$ . Since  $0 < \gamma < d(Tx_1, Tx_0)$ , there are  $\eta_1 > 0$  and  $\zeta_1 \in \mathbb{N}$  such that  $\psi_{\zeta_1}(t) \leq \gamma$  for all  $t \in [\gamma, \gamma + \eta_1]$ . By definition of  $\gamma$ , there is  $\zeta_2 \in \mathbb{N}$  such that  $M(x_{\zeta_2+1}, x_{\zeta_2}) = d(Tx_{\zeta_2}, Tx_{\zeta_2-1}) < \gamma + \eta_1$ . Therefore,  $d(Tx_{\zeta_2+\zeta_1}, Tx_{\zeta_2+\zeta_1-1}) < \psi_{\zeta_1}(M(x_{\zeta_2+1}, x_{\zeta_2})) \leq \gamma$ , a contradiction.

If one assumes  $\{Tx_n\}$  is not a backward-Cauchy sequence, there would exist  $\epsilon > 0$  and increasing sequences  $\{m_k\}$  and  $\{n_k\}$  of positive integers such that for all  $k \in \mathbb{N}$ ,  $m_k < n_k$ ,  $d(Tx_{n_k}, Tx_{m_k}) \geq \epsilon$  and  $d(Tx_{n_k-1}, Tx_{m_k}) < \epsilon$ . By the triangle inequality,

$$d(Tx_{n_k}, Tx_{m_k}) \leq d(Tx_{n_k}, Tx_{n_k-1}) + d(Tx_{n_k-1}, Tx_{m_k}),$$

and as  $k \rightarrow \infty$ ,  $d(Tx_{n_k}, Tx_{m_k}) \rightarrow \epsilon$ . Therefore, letting  $k \rightarrow \infty$  in the following

$$\begin{aligned} d(Tx_{n_k}, Tx_{m_k}) &< \psi_1(M(x_{n_k}, x_{m_k})) \\ &= \psi_1 \left( \max \left\{ d(Tx_{n_k-1}, Tx_{m_k-1}), d(Tx_{n_k-1}, Tx_{n_k}), \right. \right. \\ &\quad \left. \left. d(Tx_{m_k-1}, Tx_{m_k}), \frac{d(Tx_{n_k-1}, Tx_{m_k}) + d(Tx_{m_k-1}, Tx_{n_k})}{2} \right\} \right), \end{aligned}$$

hence as  $k \rightarrow \infty$ ,  $\beta \leq \psi_1(\beta) < \beta$ , a contradiction. Thus  $\{Tx_n\}$  is a backward-Cauchy sequence.

The sequence  $\{Tx_n\}$  is both forward and backward Cauchy hence it is a Cauchy sequence.

If  $f(Y)$  is complete, then the Cauchy sequence  $\{Tx_n\}$  as a Cauchy sequence in  $f(Y)$  converges to some element  $f(u)$ , where  $u \in Y$ . If there is  $n_0 \geq 0$  such that  $M(x_{n_0}, u) = 0$ , then  $fu = Tu$ . Otherwise, for each  $n \in \mathbb{N}$ ,

$$\begin{aligned} d(Tx_n, Tu) &< \psi_1(M(x_n, u)) \\ &= \psi_1 \left( \max \left\{ d(fx_n, fu), d(fx_n, Tx_n), d(fu, Tu), \frac{d(fx_n, Tu) + d(fu, Tx_n)}{2} \right\} \right). \end{aligned}$$

Taking  $n \rightarrow \infty$ ,  $d(fu, Tu) \leq \psi_1(\max\{d(fu, Tu)\})$ , hence  $d(fu, Tu) = 0$  and  $fu = Tu$ . The same conclusion is easily obtained if  $T(Y)$  is assumed to be complete.

**Second step:** We prove that if  $Y = X$ , then  $T$  and  $f$  have a unique common fixed point provided  $T$  and  $f$  are weakly compatible.

$Tu = fu$  and  $T$  and  $f$  are weakly compatible, hence  $Tfu = fTu$  and in fact,  $TTu = Tfu = fTu = ffu$ .

Suppose  $TTu \neq Tu$ . Then  $M(u, Tu) > 0$  and since  $Tu \in (Tf^{-1})^0(Tu)$  and  $T(Tu) \in (Tf^{-1})^0(T(Tu))$ ,

$$\begin{aligned} d(Tu, TTu) &\leq \psi_1(M(u, Tu)) \\ &= \psi_1 \left( \max \left\{ d(fu, fTu), d(fu, Tu), d(fTu, TTu), \frac{d(fu, TTu) + d(fTu, Tu)}{2} \right\} \right) \\ &= \psi(\max\{d(Tu, TTu)\}). \end{aligned}$$

Thus  $d(Tu, TTu) = 0$ , so  $Tu = TTu = fTu$ . Therefore,  $z := Tu$  is a common fixed point of  $T$  and  $f$ .

To prove the uniqueness of the common fixed point of  $T$  and  $f$ , we assume  $v$  to be another common fixed point of  $T$  and  $f$  such that  $Tu \neq v$ . Then:

$$\begin{aligned} d(z, v) = d(Tz, Tv) &\leq \psi_1(M(z, v)) \\ &\leq \psi_1 \left( \max \left\{ d(fz, fv), d(fz, Tz), d(fv, Tv), \frac{d(fv, Tz) + d(fz, Tv)}{2} \right\} \right) \\ &= \psi_1 \left( \max \left\{ d(z, v), \frac{d(v, z) + d(z, v)}{2} \right\} \right) \end{aligned}$$



which implies that

$$d(z, v) < \frac{d(v, z) + d(z, v)}{2}. \quad (2.12)$$

Similarly,

$$\begin{aligned} d(v, z) = d(Tv, Tz) &\leq \psi_1(M(v, z)) \\ &\leq \psi_1\left(\max\left\{d(fv, fz), d(Tv, fv), d(Tz, fz), \frac{d(Tv, fz) + d(Tz, fv)}{2}\right\}\right) \\ &\leq \psi_1\left(\max\left\{d(v, z), \frac{d(v, z) + d(z, v)}{2}\right\}\right) \end{aligned}$$

which implies that

$$d(v, z) < \frac{d(v, z) + d(z, v)}{2}. \quad (2.13)$$

Combining inequalities (2.12) and (2.13),  $d(v, z) + d(z, v) < d(v, z) + d(z, v)$ , a contradiction. Thus  $z = v$ : the common fixed point is unique.  $\square$

Note that Theorem 2.5 provides an erratum to the result of Singh et al. [14] in metric spaces:

**Theorem 2.6.** *Let  $(X, d)$  be a metric space and  $T, f : Y \rightarrow X$  such that  $T(Y) \subseteq f(Y)$ . Let  $T$  be a GACMK with respect to  $f$ , i.e., such that for all  $n \in \mathbb{N}$  and  $x, y \in Y$  such that  $M(x, y) > 0$ ,*

$$d(u, v) < \psi_n(M(x, y))$$

for any  $u \in (Tf^{-1})^{n-1}(Tx)$  and  $v \in (Tf^{-1})^{n-1}(Ty)$ , where

$$M(x, y) = \max\left\{d(fx, fy), d(fx, Tx), d(fy, Ty), \frac{d(fx, Ty) + d(fy, Tx)}{2}\right\}.$$

and  $\{\psi_n\}$  is a sequence of self-maps on  $[0, \infty)$  such that:

$$(P_1) \limsup_{n \rightarrow \infty} \psi_n(\epsilon) \leq \epsilon \text{ for all } \epsilon \geq 0;$$

$$(P_2) \text{ for each } \epsilon > 0, \text{ there exist } \delta > 0 \text{ and } \nu \in \mathbb{N} \text{ such that } \psi_\nu(t) \leq \epsilon \text{ for all } t \in [\epsilon, \epsilon + \delta].$$

If  $T(Y)$  or  $f(Y)$  is a complete subspace of  $X$ , then  $T$  and  $f$  have a coincidence point. Further, if  $Y = X$ , then  $T$  and  $f$  have a unique common fixed point provided that  $T$  and  $f$  commute at a coincidence point.

*Proof.* The Theorem follows from Theorem 2.5. The condition  $(G_4)$  is automatically satisfied in a metric space given the symmetry of a metric.  $\square$

A careful analysis of the proof of Theorem 2.5 reveals that condition  $(G_4)$  is not necessary if  $M(x, y)$  is replaced with  $\max\{d(fx, fy), d(fx, Tx), d(fy, Ty)\}$ . Therefore, we have the following result:

**Theorem 2.7.** *Let  $(X, d)$  be a quasi-metric space and  $T, f : Y \rightarrow X$  such that  $T(Y) \subseteq f(Y)$ . Let  $T$  be a GACMK with respect to  $f$ , i.e., such that for all  $n \in \mathbb{N}$  and  $x, y \in Y$  such that  $\{d(fx, fy), d(fx, Tx), d(fy, Ty)\} \neq \{0\}$ ,*

$$d(u, v) < \psi_n(\max\{d(fx, fy), d(fx, Tx), d(fy, Ty)\})$$

for any  $u \in (Tf^{-1})^{n-1}(Tx)$  and  $v \in (Tf^{-1})^{n-1}(Ty)$ , where

$$M(x, y) = \max\left\{d(fx, fy), d(fx, Tx), d(fy, Ty), \frac{d(fx, Ty) + d(fy, Tx)}{2}\right\}.$$

and  $\{\psi_n\}$  is a sequence of self-maps on  $[0, \infty)$  such that:

$$(G_1) \limsup_{n \rightarrow \infty} \psi_n(\epsilon) \leq \epsilon \text{ for all } \epsilon \geq 0;$$

$$(G_2) \text{ for each } \epsilon > 0, \text{ there exist } \delta > 0 \text{ and } \nu \in \mathbb{N} \text{ such that } \psi_\nu(t) \leq \epsilon \text{ for all } t \in [\epsilon, \epsilon + \delta].$$

If  $T(Y)$  or  $f(Y)$  is a complete subspace of  $X$ , then  $T$  and  $f$  have a coincidence point. Further, if  $Y = X$ , then  $T$  and  $f$  have a unique common fixed point provided that  $T$  and  $f$  commute at a coincidence point.



### 3 A fixed point theorem for asymptotic quasi-contractions

In this section, we consider the case where there is a real number  $c \in (0, 1)$  such that  $\psi_n(t) = ct$  for all  $t \in [0, \infty)$  and every  $n \in \mathbb{N}$ , albeit,  $M(x, y)$  is further relaxed.

**Theorem 3.1.** *Let  $(X, d)$  be a quasi-metric space and  $T, f : Y \rightarrow X$  such that  $T(Y) \subseteq f(Y)$ . Suppose also that there is  $c \in (0, 1)$  such that for all  $n \in \mathbb{N}$  and  $x, y \in Y$  with  $M(x, y) > 0$ ,*

$$d(u, v) \leq cM(x, y) \tag{3.1}$$

for any  $u \in (Tf^{-1})^{n-1}(Tx)$  and  $v \in (Tf^{-1})^{n-1}(Ty)$ , where

$$M(x, y) = \max \left\{ \begin{array}{l} d(fx, fy), d(fy, fx), d(fx, Tx), d(Tx, fx), d(fy, Ty), \\ d(Ty, fy), d(fx, Ty), d(Ty, fx), d(fy, Tx), d(Tx, fy) \end{array} \right\}. \tag{3.2}$$

If  $T(Y)$  or  $f(Y)$  is  $\{T, f\}$ -orbitally complete, then  $T$  and  $f$  have a coincidence point. Further, if  $Y = X$ , then  $T$  and  $f$  have a unique common fixed point provided that  $T$  and  $f$  commute at a coincidence point.

*Proof.* Let  $x_0 \in Y$  be arbitrary chosen. Since  $T(Y) \subset f(Y)$ , we can define a Jungck sequence  $\{x_n\}$  of points in  $Y$  such that

$$Tx_n = fx_{n+1}, \quad n = 0, 1, 2, \dots$$

**Step 1:** Suppose  $T(Y)$  or  $f(Y)$  is  $\{T, f\}$ -orbitally complete. We want to show that  $T$  and  $f$  have a coincidence point. We distinguish two cases:

**Case 1:** If there is  $n \geq 0$  such that  $Tx_n = Tx_{n+1}$ , then  $x_{n+1}$  is a coincidence point of  $T$  and  $f$ , since  $fx_{n+1} = Tx_{n+1}$ .

**Case 2:** Suppose now that  $Tx_n \neq Tx_{n+1}$  for all  $n \geq 0$ . For any  $n \geq 0$ , we have  $d(fx_{n+1}, Tx_{n+1}) = d(Tx_n, Tx_{n+1}) > 0$ , hence  $M(x_i, x_j) > 0$  for any distinct  $i, j \geq 0$ .

If we let  $D(x, y) = \max \{d(x, y), d(y, x)\}$  for all  $x, y \in X$ , the pair  $(X, D)$  is a metric space and conditions (3.12) and (3.4) become for all  $x, y \in X$  such that  $N(x, y) > 0$ :

$$D(u, v) \leq cN(x, y) \tag{3.3}$$

for all  $u \in (Tf^{-1})^{n-1}(Tx)$  and  $v \in (Tf^{-1})^{n-1}(Ty)$ , where

$$N(x, y) = \max \{D(fx, fy), D(fx, Tx), D(fy, Ty), D(fx, Ty), D(fy, Tx)\}. \tag{3.4}$$

Let  $n \geq 2$  and  $i, j \geq 1$  such that  $1 \leq i < j \leq n$ .

Since  $Tx_i \in (Tf^{-1})^{i-1}(Tx_1)$ ,  $Tx_j \in (Tf^{-1})^{j-1}(Tx_{j-i+1})$ , and  $M(x_1, x_{j-i+1}) > 0$ , we have that

$$\begin{aligned} D(Tx_i, Tx_j) &\leq cN(x_1, x_{j-i+1}) \\ &\leq c \max \left\{ \begin{array}{l} D(Tx_0, Tx_{j-i}), D(Tx_0, Tx_1), D(Tx_{j-i}, Tx_{j-i+1}), \\ D(Tx_0, Tx_{j-i+1}), D(Tx_{j-i}, Tx_1) \end{array} \right\} \\ &\leq c \mathbf{diam}(O_{T,f}(Tx_0, n)), \end{aligned} \tag{3.5}$$

where

$$\mathbf{diam}(O_{T,f}(Tx_0, n)) := \sup \{D(z_1, z_2) : z_1, z_2 \in O_{T,f}(Tx_0, n)\}.$$

In particular, for all  $n \geq 2$ ,

$$D(Tx_1, Tx_n) \leq c \mathbf{diam}(O_{T,f}(Tx_0, n)).$$

Given  $n \geq 1$ ,  $O_{T,f}(Tx_0, n)$  is finite hence, there is  $m \in \{2, 3, \dots, n\}$  such that

$$D(Tx_0, Tx_m) = \mathbf{diam}(O_{T,f}(Tx_0, n)). \tag{3.6}$$

Now, for  $n \geq 3$ ,

$$\begin{aligned} D(Tx_1, Tx_m) &\leq cN(x_1, x_m) \\ &= c \max \left\{ \begin{array}{l} D(Tx_0, Tx_{m-1}), D(Tx_0, Tx_1), D(Tx_{m-1}, Tx_m), \\ D(Tx_0, Tx_m), D(Tx_{m-1}, Tx_1) \end{array} \right\} \end{aligned}$$

hence  $m > 2$ ,

$$\max \left\{ \begin{array}{l} D(Tx_0, Tx_{m-1}), D(Tx_0, Tx_1), D(Tx_{m-1}, Tx_m), \\ D(Tx_0, Tx_m), D(Tx_{m-1}, Tx_1) \end{array} \right\} = D(Tx_0, Tx_m),$$

so  $D(Tx_1, Tx_m) \leq cD(Tx_0, Tx_m)$  and

$$\begin{aligned} D(Tx_0, Tx_m) &\leq D(Tx_0, Tx_1) + D(Tx_1, Tx_m) \\ &\leq D(Tx_0, Tx_1) + cD(Tx_0, Tx_m). \end{aligned}$$

Therefore,

$$D(Tx_0, Tx_m) \leq \frac{1}{1-c} D(Tx_0, Tx_1). \quad (3.7)$$

From (3.6) and (3.7), the sequence  $\{\mathbf{diam}(O_{T,f}(Tx_0, n))\}_{n \geq 3}$  is bounded above; since it is also increasing, it converges to the positive number  $\mathbf{diam}(O_{T,f}(Tx_0, \infty))$ .

To show that  $\{Tx_n\}$  is a Cauchy sequence, let  $n, m \in \mathbb{N}$  with  $n < m$ . Since  $Tx_n \in (Tf^{-1})^0(Tx_n)$ ,  $Tx_m \in (Tf^{-1})^0(Tx_m)$ , and  $M(x_n, x_m) > 0$ , we have that

$$\begin{aligned} D(Tx_n, Tx_m) &\leq cN(x_n, x_m) \\ &\leq c \max \left\{ \begin{array}{l} D(Tx_{n-1}, Tx_{m-1}), D(Tx_{n-1}, Tx_n), \\ D(Tx_{m-1}, Tx_m), D(Tx_{n-1}, Tx_m), D(Tx_{m-1}, Tx_n) \end{array} \right\} \\ &\leq c \mathbf{diam}(O_{T,f}(Tx_{n-1}, m - n + 1)). \end{aligned} \quad (3.8)$$

Repeating the argument that led to (3.6), there is  $m_1 \in \{2, 3, \dots, m - n + 1\}$  such that

$$D(Tx_{n-1}, Tx_{n-1+m_1}) = \mathbf{diam}(O_{T,f}(Tx_{n-1}, m - n + 1)). \quad (3.9)$$

Thus, from (3.8),

$$\begin{aligned} D(Tx_n, Tx_m) &\leq c \mathbf{diam}(O_{T,f}(Tx_{n-1}, m - n + 1)) \\ &= cD(Tx_{n-1}, Tx_{n-1+m_1}) \\ &\leq c^2 \mathbf{diam}(O_{T,f}(Tx_{n-2}, m_1 + 1)) \\ &\leq c^2 \mathbf{diam}(O_{T,f}(Tx_{n-2}, m - n + 2)) \end{aligned} \quad (3.10)$$

Repeating the process, one obtains:

$$\begin{aligned} D(Tx_n, Tx_m) &\leq c^n \mathbf{diam}(O_{T,f}(Tx_0, m)) \\ &\leq c^n \mathbf{diam}(O_{T,f}(Tx_0, \infty)). \end{aligned}$$

Thus, as  $n, m \rightarrow \infty$ ,  $D(Tx_n, Tx_m) \rightarrow 0$ , hence  $\{Tx_n\}$  is a Cauchy sequence in  $X$ .  $f(Y)$  or  $T(Y)$  being  $\{T, f\}$ -orbitally complete,  $\{Tx_n\}$  has a limit, say  $fu$ , where  $u \in X$ . Suppose that  $fu \neq Tu$ ; then  $N(u, x_n) > 0$  for all  $n \geq 1$ , and

$$\begin{aligned} D(Tu, Tx_n) &\leq cN(u, x_n) \\ &= c \max \left\{ \begin{array}{l} D(fu, Tx_{n-1}), D(fu, Tu), D(Tx_{n-1}, Tx_n), \\ D(Tx_{n-1}, Tu), D(fu, Tx_n) \end{array} \right\}. \end{aligned} \quad (3.11)$$

Thus, as  $n \rightarrow \infty$ ,  $D(Tu, fu) \leq cD(fu, Tu)$ , a contradiction. Thus  $D(Tu, fu) = 0$  and  $Tu = fu$ .  $u$  is a coincidence point of  $T$  and  $f$ .

**Step 2:** Now, we show that if  $Y = X$ , then  $T$  and  $f$  have a unique common fixed point.

$Tu = fu$ , and  $T$  and  $f$  commute at their coincidence point  $u$ , hence  $TTu = Tfu = fTu = ffu$ . Therefore, if one supposes that  $Tu \neq TTu$ , then  $N(u, Tu) > 0$  and

$$D(Tu, TTu) \leq cN(u, Tu) = cD(Tu, TTu),$$

a contradiction. Therefore  $D(Tu, TTu) = 0$  and  $TTu = Tu = fTu$ :  $Tu$  is a common fixed point of  $T$  and  $f$ .

**Step 3:** To show that  $z := Tu$  is the only common fixed point of  $T$  and  $f$ , suppose  $v$  is another a common fixed point of the pair  $\{T, f\}$ . We have that  $z \neq v$  so  $N(z, v) > 0$  and

$$D(z, v) = D(Tz, Tv) \leq cN(z, v) = cD(z, v),$$

a contradiction. Thus  $D(z, v) = 0$  and  $z = v$ . □

The following corollary holds in metric spaces:

**Corollary 3.2.** *Let  $(X, d)$  be a metric space and  $T, f : Y \rightarrow X$  mappings such that  $T(Y) \subseteq f(Y)$ . Suppose also that there is  $c \in (0, 1)$  such that for all  $n \in \mathbb{N}$  and  $x, y \in Y$  with  $M(x, y) > 0$ ,*

$$d(u, v) \leq cM(x, y) \tag{3.12}$$

for any  $u \in (Tf^{-1})^{n-1}(Tx)$  and  $v \in (Tf^{-1})^{n-1}(Ty)$ , where

$$M(x, y) = \max \{d(fx, fy), d(fx, Tx), d(fy, Ty), d(fx, Ty), d(fy, Tx)\}. \tag{3.13}$$

If  $T(Y)$  or  $f(Y)$  is  $\{T, f\}$ -orbitally complete, then  $T$  and  $f$  have a coincidence point. Further, if  $Y = X$ , then  $T$  and  $f$  have a unique common fixed point provided that  $T$  and  $f$  commute at a coincidence point.

## 4 Example

To validate the results obtained, we construct the following example of the applicability of Theorem 2.5.

**Example 4.1.** *Let  $X = [1, 2]$  be equipped with the usual metric  $d(x, y) = |x - y|$ . Let  $T, f : X \rightarrow X$  be defined by:  $Tx = \frac{x+2}{3}$  and  $fx = \frac{x+1}{2}$  for all  $x \in [1, 2]$ . Here,  $T(X) = [1, \frac{4}{3}]$  and  $f(X) = [1, \frac{3}{2}]$  hence  $T(X) \subset f(X)$ . Here,  $f$  is bijective, and  $f^{-1}(x) = 2x - 1$  for all  $x \in [1, \frac{3}{2}]$ . Therefore,  $(Tf^{-1})(x) = \frac{2x+1}{3}$  for all  $x \in [1, \frac{3}{2}]$  and for all  $n \geq 0$ ,  $(Tf^{-1})^n(x) = (\frac{2}{3})^n(x-1) + 1$  for all  $x \in [1, \frac{3}{2}]$ .*

$$(Tf^{-1})^n(x) = \begin{cases} 1 & \text{if } x = 1, \\ (\frac{2}{3})^n(x-1) + 1 & \text{if } x \in (1, \frac{3}{2}], \end{cases}$$

One can check that for all  $n \geq 1$ , and  $x, y \in [1, \frac{3}{2}]$ ,

$$d((Tf^{-1})^n(x), (Tf^{-1})^n(y)) = \left(\frac{2}{3}\right)^n |x - y|.$$

In particular, for all  $n \geq 0$  and  $x, y \in [1, 2]$ ,

$$d((Tf^{-1})^{n-1}(Tx), (Tf^{-1})^{n-1}(Ty)) = \left(\frac{2}{3}\right)^{n-1} \left| \frac{x-y}{3} \right|.$$

Moreover,  $d(fx, fy) = \frac{1}{2}|x - y|$  for  $x \in [1, 2]$ . Therefore, for all  $x, y \in [1, 2]$  such that  $M(x, y) > 0$ ,

$$d((Tf^{-1})^{n-1}(Tx), (Tf^{-1})^{n-1}(Ty)) = \left(\frac{2}{3}\right)^n d(fx, fy) < \psi_n(M(x, y)),$$

where

$$\psi_n(t) = 2 \left(\frac{2}{3}\right)^n t \quad \forall t \geq 0.$$

One can check that  $\{\psi_n\}$  satisfies conditions  $(G_1)$  and  $(G_2)$  of Theorem 2.5 since for all  $\epsilon \geq 0$ ,  $\limsup_{n \rightarrow \infty} \psi_n(\epsilon) = 0 \leq \epsilon$ , and if  $\epsilon > 0$ ,  $\delta = \frac{\epsilon}{8}$ , and  $\nu = 2$ , then  $\psi_\nu(t) \leq \epsilon$  for all  $t \in [\epsilon, \epsilon + \delta]$ .

In addition,  $T$  and  $f$  commute at their only coincidence point  $x = 1$  hence all the conditions of Theorem 2.5 hold. Therefore,  $T$  and  $f$  have a unique common fixed point. It is easily seen that  $x = 1$  is the only common fixed point of  $T$  and  $f$ . Given  $x_0 \in [1, 2]$ , consider the Jungck sequence  $Tx_n = fx_{n+1}$ . In the uninteresting case that  $x_0 = 1$ ,  $x_n = 1$  for any  $n \geq 1$ . Now, let  $x_0 \in (1, 2]$ . Then  $3x_{n+1} = 2x_n + 1$  for all  $n \geq 0$ . A quick computation gives the following formula for any  $n \geq 1$ :

$$x_n = \left(\frac{2}{3}\right)^n (x_0 - 1) + 1$$

$$Tx_n = \frac{1}{3} \left(\frac{2}{3}\right)^n (x_0 - 1) + 1.$$

Thus  $\{Tx_n\}$  converges to  $T(1) = 1$ , the common fixed point of the pair  $\{T, f\}$ .

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